

DAFTAR ISI

| | |
|----------------------------------|-------|
| Halaman Judul | i |
| Lembar Pengesahan | ii |
| Pernyataan Orisinalitas..... | iii |
| <i>Abstract</i> | iv |
| Abstrak | v |
| Kata Pengantar | vi |
| Lembar Ucapan Terima Kasih | vii |
| Daftar Isi | ix |
| Daftar Gambar | xii |
| Daftar Tabel | xiv |
| Daftar Singkatan..... | xv |
| Daftar Istilah..... | xvi |
| Daftar Lampiran | xviii |

BAB I PENDAHULUAN

| | |
|---------------------------------|---|
| 1.1 Latar Belakang | 1 |
| 1.2 Rumusan Masalah..... | 1 |
| 1.3 Tujuan..... | 2 |
| 1.4 Batasan Masalah | 2 |
| 1.5 Metodologi Penelitian | 3 |
| 1.6 Sistematika Penulisan | 3 |

BAB II DASAR TEORI

| | |
|---------------------------------|----|
| 2.1 Konsep Dasar Robot..... | 5 |
| 2.1.1 Teknik Disain Robot..... | 6 |
| 2.1.2 Sistem Kontrol Robot..... | 9 |
| 2.2 Sensor..... | 11 |
| 2.2.1 Sensor Limit Switch..... | 15 |
| 2.2.2 Sensor Infra Merah..... | 15 |
| 2.3 Motor DC..... | 16 |

| | | |
|-------|--|----|
| 2.4 | Mikrokontroler ATmega8535..... | 16 |
| 2.4.1 | Fitur Mikrokontroler ATmega8535..... | 17 |
| 2.4.2 | Konfigurasi Pin Mikrokontroler ATmega8535..... | 17 |
| 2.4.3 | Arsitektur Mikrokontroler ATmega8535..... | 18 |
| 2.5 | Pemrograman Bahasa C..... | 19 |
| 2.6 | Code Vision AVR Eval..... | 20 |

BAB III PERANCANGAN DAN REALISASI SISTEM

| | | |
|---------|-----------------------------------|----|
| 3.1 | Alur Perancangan..... | 22 |
| 3.2 | Konsep Dasar Robot..... | 22 |
| 3.3 | Perancangan Lapangan..... | 23 |
| 3.4 | Perancangan Mekanik Robot..... | 24 |
| 3.3.1 | Konstruksi Fisik..... | 24 |
| 3.3.2 | Rangkaian Elektronik..... | 24 |
| 3.3.2.1 | Sistem Minimum..... | 25 |
| 3.3.2.2 | Driver Motor..... | 26 |
| 3.3.2.3 | Sensor Inframerah..... | 27 |
| 3.3.2.4 | Catu Daya..... | 31 |
| 3.3.2.5 | Sensor Limit Switch..... | 31 |
| 3.3.2.6 | Optocoupler..... | 33 |
| 3.4 | PWM (Pulse Width Modulation)..... | 33 |
| 3.5 | Perancangan Program..... | 34 |
| 3.4.1 | Algoritma Program..... | 35 |
| 3.4.2 | Program Robot..... | 39 |

BAB IV PENGUJIAN DAN PENGUKURAN SISTEM

| | | |
|-------|------------------------------|----|
| 4.1 | Pengukuran Sensor..... | 40 |
| 4.2.1 | Sensor Inframerah..... | 40 |
| 4.2.2 | Sensor Limit Switch..... | 40 |
| 4.2 | Pengukuran Driver Motor..... | 41 |
| 4.3 | Pengukuran Optocoupler..... | 42 |

| | | |
|-----|---------------------------------------|----|
| 4.4 | Pengukuran PWM..... | 42 |
| 4.5 | Pengujian Kecepatan Putaran Roda..... | 45 |
| 4.6 | Pengujian Respon Program..... | 45 |
| 4.7 | Pengukuran Konsumsi Daya..... | 46 |

BAB V KESIMPULAN DAN SARAN

| | | |
|-----|------------------|----|
| 5.1 | Kesimpulan | 47 |
| 5.2 | Saran | 47 |

DAFTAR PUSTAKA

LAMPIRAN A

Gambar Skematik Rangkaian

LAMPIRAN B

Program C Sistem

LAMPIRAN C

Data Sheet Komponen