

## TABLE OF CONTENTS

<b>ABSTRACT .....</b>	i
<b>PREFACE.....</b>	ii
<b>ACKNOWLEDGEMENTS .....</b>	iii
<b>TABLE OF CONTENTS .....</b>	v
<b>TABLE OF FIGURES.....</b>	vii
<b>TABLE OF TABLES.....</b>	viii
1.1    Background Problems .....	1
1.2.    Problem Formulation .....	2
1.3.    Objectives .....	2
1.4.    Benefits of Research Results.....	2
1.5.    Scope of Problem.....	3
1.6.    Research Method .....	3
1.7.    User Projection .....	4
<b>CHAPTER II LITERATURE REVIEW .....</b>	5
2.1.    Research Gap .....	5
2.2.    Design Concept Solution .....	7
2.3.    Radio Detection and Ranging (Radar).....	8
2.4.    Frequency Modulated Continuous Wave (FMCW).....	8
2.5.    Fast Fourier Transform (FFT).....	9
2.6.    Image Depth Estimation.....	10
2.7.    Generative Adversarial Network (GAN) .....	11
2.8.    Pose Estimation.....	11
2.9.    Camera Distance Evaluation.....	12
2.10.    U-Net.....	13
2.11.    Convolutional Neural Network (CNN).....	13
2.11.1.    Convolutional Layer .....	14

2.11.2. Rectified Linear Units (ReLU) Activation.....	14
2.11.3. Pooling Layer.....	15
<b>CHAPTER III SYSTEM DESIGN.....</b>	<b>16</b>
3.1. System Design .....	16
3.1.1. Block Diagram.....	16
3.1.2. Function and Features .....	17
3.2. Hardware Design .....	17
3.2.1. Component Specifications .....	18
3.3. Software Design.....	20
3.3.1. Flowchart Radar Signal Data Proccess .....	21
3.3.2. Flowchart Camera Data Proces .....	22
<b>CHAPTER IV RESULT AND ANALYSIS .....</b>	<b>23</b>
4.1. Experiment Results .....	23
4.2. Preprocessing Data.....	25
4.3. Architecture GAN Model.....	26
4.4. Data Processing.....	28
4.6. Implementation System.....	31
4.7. Market Analysis .....	32
4.7.1. Total System Design Expenses.....	32
4.7.2. Target Marketing For System .....	34
<b>CHAPTER V CONCLUSION .....</b>	<b>35</b>
5.1. Conclusion .....	35
5.2. Suggestion.....	35
<b>REFERENCES.....</b>	
<b>ATTACHMENT.....</b>	