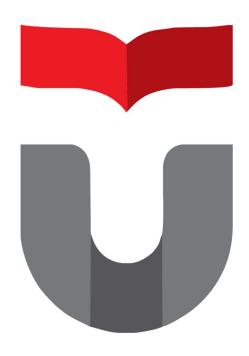# ACCURACY IMPROVEMENT OF CAMERA AND LIDAR LOCALIZATION BASED ON 3D POINT CLOUD USING MODIFIED CONVOLUTIONAL NEURAL NETWORKS

A THESIS SUBMITTED TO

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