

**APPROVAL PAGE**

**MASTER'S THESIS**

**DESIGN AND CONTROL OF MULTI ROBOT AGV PROTOTYPE  
MANUEVER CONTROL BASED ON INVERTED CAMERA**

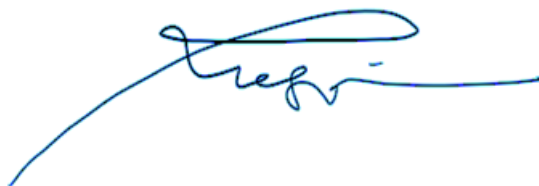
**This Thesis is approved and authorized to be filed in The Graduate Program of  
Electrical Engineering, Telkom University**

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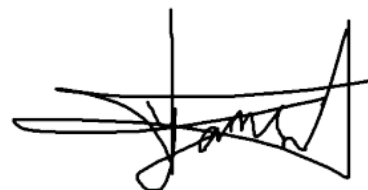
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