

DAFTAR PUSTAKA

- [1] S. Osswald, D. Wurhofer, S. Trösterer, E. Beck, and M. Tscheligi, “Predicting information technology usage in the car: Towards a car technology acceptance model,” in *AutomotiveUI 2012 - 4th International Conference on Automotive User Interfaces and Interactive Vehicular Applications, In-cooperation with ACM SIGCHI - Proceedings*, 2012, pp. 51–58. doi: 10.1145/2390256.2390264.
- [2] L. G. Guntrum, S. Schwartz, and C. Reuter, “Dual-Use Technologies in the Context of Autonomous Driving: An Empirical Case Study From Germany,” *Zeitschrift für Außen- und Sicherheitspolitik*, vol. 16, no. 1, pp. 53–77, Mar. 2023, doi: 10.1007/s12399-022-00935-3.
- [3] D. W. Gage, “UGV HISTORY 101: A Brief History of Unmanned Ground Vehicle (UGV) Development Efforts.”
- [4] S. Odedra, S. D. Prior, and M. Karamanoglu, “Investigating the mobility of unmanned ground vehicles Motion Driven eXperience View project Tethered Drones for Surveillance Applications View project,” 2009. [Online]. Available: <https://www.researchgate.net/publication/229028828>
- [5] N. A. Prasetyo and D. Herianto, “Proceeding Seminar Nasional Tahunan Teknik Mesin XV (SNTTM XV) PERANCANGAN KENDARAAN TANPA AWAK (UNMANNED GROUND VEHICLE) UNTUK MISI PEMANTAUAN BENCANA.”
- [6] M. Fandhi, A. Triwiyatno, and D. B. Setiyono, “HUMAN MACHINE INTERFACE SISTEM KONTROL AUTOPILOT UGV (UNMANNED GROUND VEHICLE).”
- [7] T. Gamer, M. Hoernicke, B. Kloepffer, R. Bauer, and A. J. Isaksson, “The autonomous industrial plant – future of process engineering, operations and maintenance,” *J Process Control*, vol. 88, pp. 101–110, Apr. 2020, doi: 10.1016/j.jprocont.2020.01.012.
- [8] A. J. Lubbe and P. Kluge, “DEVELOPMENT AND TESTING OF A WIRELESS CONTROLLED CAR USING THE INTERNET AS COMMUNICATION MEDIUM,” 2008.
- [9] G. Martinic, “The proliferation, diversity and utility of ground-based robotic technologies. The Proliferation, Diversity and Utility of Ground-based Robotic Technologies,” 2014. [Online]. Available: <https://www.researchgate.net/publication/283723983>

- [10] M. Mahbub, “Design and Implementation of Multipurpose Radio Controller Unit Using nRF24L01 Wireless Transceiver Module and Arduino as MCU,” *International Journal of Digital Information and Wireless Communications*, vol. 9, no. 2, pp. 61–72, 2019, doi: 10.17781/P002598.
- [11] M. Sun *et al.*, *Proceedings of 2017 IEEE 6th Data Driven Control and Learning Systems Conference (DDCLS'17) : Chongqing, China, May 26-27, 2017*.
- [12] Wahyu Ristanto, “ANALISIS AKURASI PENENTUAN POSISI RECEIVER HI TARGET V 30 BERDASARKAN PENGGUNAAN SATELIT GPS, GLONASS DAN BEIDOU”.
- [13] D. Mali, R. T. Patil, N. Dharwadkar, C. R. Devale, and O. Tembhurne, “Real-Time Smart Surveillance System Using Raspberry Pi.” [Online]. Available: <https://ssrn.com/abstract=3357807>
- [14] A. S. Shibghatullah, A. Jalil, M. H. A. Wahab, J. N. P. Soon, K. Subaramaniam, and T. Eldabi, “Vehicle Tracking Application Based on Real Time Traffic,” *International Journal of Electrical and Electronic Engineering and Telecommunications*, vol. 11, no. 1, pp. 67–73, Jan. 2022, doi: 10.18178/ijeetc.11.1.67-73.
- [15] D. C. Ganskopp and D. D. Johnson, “GPS Error in studies addressing animal movements and activities,” *Rangel Ecol Manag*, vol. 60, no. 4, pp. 350–358, 2007, doi: 10.2111/1551-5028(2007)60[350:GEISAA]2.0.CO;2.