

## DAFTAR SINGKATAN

1D	1 Dimensi
2D	2 Dimensi
3D	3 Dimensi
LiDAR	<i>Light Detection and Ranging</i>
AP	<i>Average Precision</i>
mAP	<i>Mean Average Precision</i>
RGB	<i>Red Green Blue</i>
CNN	<i>Convolutional Neural Network</i>
W	<i>Network Width</i>
H	<i>Network Height</i>
C	<i>Channel</i>
TP	<i>True Positive</i>
TN	<i>True Negative</i>
FP	<i>False Positive</i>
FN	<i>False Negative</i>