

DAFTAR PUSTAKA

- [1] L. Meier, P. Tanskanen, F. Fraundorfer, and M. Pollefeys, "THE PIXHAWK OPEN-SOURCE COMPUTER VISION FRAMEWORK FOR MAVS," *The International Archives of the Photogrammetry, Remote Sensing and Spatial Information Sciences*, vol. XXXVIII-1/C22, pp. 13–18, Sep. 2012, doi: 10.5194/isprsarchives-XXXVIII-1-C22-13-2011.
- [2] J. Rahimatullah, N. Rachman, S. Muda, I. Fahmi, and Z. Akbari, "Rancang Bangun Autonomous Robot Tank dengan Metode Waypoint Berbasis Raspberry Pi The Design of Autonomous Robot Tank with Waypoint Method Based on Raspberry Pi," *TELKA*, vol. 6, no. 1, pp. 29–39, 2020.
- [3] S. M. Yusviva and I. N. Sutantra, "Analisis Pengaruh Parameter Operasional Terhadap Perilaku Belok dan Stabilitas Pada Panser Anoa 6X6 APC," *Jurnal Teknik ITS*, vol. 6, no. 2, Sep. 2017, doi: 10.12962/j23373539.v6i2.27948.
- [4] Alfiandy, M. T. Suprayogi, Nurwulan F, and M. Pfis, "IOT (INTERNET OF THINGS) NAVIGASI DRONE BERDASARKAN WAYPOINT IOT (INTERNET OF THINGS) NAVIGATION DRONE BASED ON WAYPOINT."
- [5] V. C. P. P. D. K. M. Hardy Samuel Saroinsong, "Rancang Bangun Wahana Pesawat Tanpa Awak (Fixed Wing) Berbasis Ardupilot," *Jurnal Teknik Elektro dan Komputer*, 2018.
- [6] Y. S. [2] Bambang Setyono [1], "RANCANG BANGUN SISTEM TRANSMISI, KEMUDI, DAN PENGGEREMAN MOBIL LISTRIK 'SEMUT ABANG,'" *Institut Teknologi Adhi Tama Surabaya*.
- [7] R. Arindya, "PENALAAAN KENDALI PID UNTUK PENGENDALI PROSES," 2086.
- [8] B. Sampurno, A. Abdurrakhman, and H. S. Had, "Sistem Kendali PID pada Pengendalian Suhu untuk Kestabilan Proses Pemanasan Minuman Sari Jagung," in *Seminar Nasional Kontrol, Instrumentasi dan Otomasi (SNIKO) 2015*, 2016, p. 242. doi: 10.5614/sniko.2015.34.
- [9] I. Pramuko, A. H. Purboputro, M. A. Saputro, and W. Setiyadi, "The 7 th University Research Colloquium 2018 STIKES PKU Muhammadiyah Surakarta."
- [10] K. M. and S. S. Yuta Susuki, "Four Wheel Steering System for Medium-Duty Trucks," *SAE International*.

- [11] H. Kurniawan, F. Fuazen, E. Sarwono, and E. Julianto, “PERENCANAAN SISTEM KEMUDI “ RACK AND PINION “, MOBIL HEMAT ENERGI SHELL ECO MARATHON ASIA 2018 EMISIA BORNEO 01,” *Suara Teknik: Jurnal Ilmiah*, vol. 9, no. 2, Sep. 2018, doi: 10.29406/stek.v9i2.1537.
- [12] F. R. Saputra and M. Rivai, “Autonomous Surface Vehicle sebagai Alat Pemantau Lingkungan Menggunakan Metode Navigasi Waypoint,” *Jurnal Teknik ITS*, vol. 7, no. 1, Mar. 2018, doi: 10.12962/j23373539.v7i1.28493.
- [13] I. Maulidin, Y. Susanthi, T. Elektro, and U. Kristen Maranatha Jln drg Surya Sumantri, “Rancang Bangun Quadcopter untuk Terbang Mengikuti Dinding Menggunakan Sensor Jarak Ultrasonik HC-SR04 Design and Realization of Quadcopter for Fly Following the Wall Using HC-SR04 Ultrasonic Sensor,” *TELKA*, vol. 6, no. 2, pp. 75–84, 2020.
- [14] Brave, “Aliran Daya Optimal Pada Sistem Minahasa_NOVA GAMA_070213016_.”
- [15] A. F. Anto and T. Sukardiyono, “Prototype Autonomous Rover Pembersih Sampah Pantai menggunakan ArduPilot,” *Elinvo (Electronics, Informatics, and Vocational Education)*, vol. 4, no. 2, pp. 202–209, Dec. 2019, doi: 10.21831/elinvo.v4i2.28793.