

DAFTAR PUSTAKA

- [1] H. Kurniawan, F. Fuazen, E. Sarwono, and E. Julianto, “Perencanaan Sistem Kemudi “ Rack and Pinion “, Mobil Hemat Energi Shell Eco Marathon Asia 2018 Emisia Borneo 01,” *Suara Tek. J. Ilm.*, vol. 9, no. 2, pp. 58–63, 2018, doi: 10.29406/stek.v9i2.1537.
- [2] A. Alamsyah, “Tanpa Dasar Ilmu Ackermann Steering Geometry Mobil Anda Enggak Bakal Bergerak Lincah,” 2018. <https://mobilmo.com/top-mobil/tanpa-dasar-ilmu-ackermann-steering-geometry-mobil-anda-enggak-bakal-bergerak-lincah-aid3638> (accessed Nov. 14, 2020).
- [3] Y. Susuki, K. Matsuda, and S. Sasaki, “Four wheel steering system for medium-duty trucks,” *SAE Tech. Pap.*, vol. 5, no. Iii, pp. 1328–1331, 1994, doi: 10.4271/942310.
- [4] P. I. Purboputro, M. A. H. M. A. Saputro, and W. Setiyadi, “Uji Kemampuan Rancangan Sistem Kemudi , Transmisi , dan Pengereman pada Mobil Listrik Prototype ‘ Ababil ,’” *Proceeding of The URECOL*, no. Proceeding of The 7th University Research Colloquium 2018: Bidang Teknik dan Rekayasa, pp. 118–127, 2018, [Online]. Available: <http://repository.urecol.org/index.php/proceeding/article/view/24>.
- [5] K. D. Artika, R. Syahyuniar, and N. Priono, “Perancangan Sistem Kemudi Manual Pada Mobil Listrik,” *J. Elem.*, vol. 4, no. 1, p. 01, 2017, doi: 10.34128/je.v4i1.1.
- [6] D. Setiawan, “Rancangbangun Robot Mobil Kontrol Sederhana Menggunakan Arduino Berbasis Android System,” *J. Sains, Teknol. dan Ind. UNILAK*, vol. 14, no. 1, pp. 101–107, 2016.
- [7] B. Setyono and Y. Setiawan, “Rancang Bangun Sistem Transmisi, Kemudi dan Pengereman Mobil Listrik ‘Semut Abang,’” *Semin. Nas. Sains dan Teknol. Terap. III 2015*, pp. 89–96, 2015.
- [8] D. I. Fajar, *Analisa Sistem Kemudi Mobil Listrik Brajawahana Its Terhadap Konsdisi*. 2015.

- [9] B. P. Resosudarmo, D. A. Nurdianto, and A. A. Yusuf, "Greenhouse Gas Emission in Indonesia: The Significance of Fossil Fuel Combustion," *Reg. Dev. Energy Environ. Indones.*, no. July 2020, pp. 146–159, 2009.
- [10] E. Grunditz and T. Thiringer, "Performance Analysis of Current BEVs Based on a Comprehensive Review of Specifications," *IEEE Trans. Transp. Electrification*, vol. 2, pp. 270–289, 2016.
- [11] M. N. Yuski, W. Hadi, and A. Saleh, "Rancang Bangun Jangkar Motor DC (The Rotor of DC Motor Design)," *Berk. Sainstek*, vol. V (2), pp. 98–103, 2017.
- [12] B. Sampurno, A. Abdurrahman, and H. S. Had, "Sistem Kendali PID pada Pengendalian Suhu untuk Kestabilan Proses Pemanasan Minuman Sari Jagung," p. 242, 2016, doi: 10.5614/sniko.2015.34.
- [13] A. Radita, "Penalaan Kendali PID untuk Pengendali Proses," *J. Teknol. Elektro, Univ. Mercu Buana*, vol. 8, no. 2, pp. 109–116, 2017.
- [14] M. Muhammad, A. Maharani, and M. Leni, "Optimasi Pengendalian Flow Control DEA Absorber Menggunakan Proportional Integral Derivative (PID) Control Dengan Metode Respon Surface Methodology (RSM)," *J. Teknol. Kim. Unimal*, vol. 7, no. 2, p. 152, 2019, doi: 10.29103/jtku.v7i2.1255.
- [15] "EXTREME 3D PRO JOYSTICK," *Logitech*, 2020.
<https://www.logitechg.com/in-id/products/space/extreme-3d-pro-joystick.942-000008.html#product-tech-specs> (accessed Dec. 23, 2020).
- [16] Asahi Kasei Microdevices Corporation, "Incremental type and absolute type." <https://www.akm.com/us/en/technology/technical-tutorial/basic-knowledge-encoder/type-mechanism-2/> (accessed Aug. 19, 2021).
- [17] L. Hakim, R. Dikairono, and T. Mujiono, "Implementasi perhitungan posisi robot dengan FPGA menggunakan rotary encoder," pp. 2–4.