DAFTAR SIMBOL

Simbol	Keterangan
x_1	*input* CLBF (sumbu x)
x_2	*input* CLBF (sumbu y)
u_1	*input* sistem integrator (v_{x_1})
u_2	*input* sistem integrator (v_{x_2})
$\mathcal{X}$	keseluruhan *state*
$\mathcal{D}$	*unsafe state*
$V(x)$	*control lyapunov function*
$B(x)$	*control barrier function*
$W(x)$	*control lyapunov-barrier function*
λ, κ, γ	parameter kendali
px	piksel