

CONTENTS

APPROVAL PAGE

ORIGINALITY STATEMENT

ABSTRACT **iv**

PREFACE **v**

ACKNOWLEDGE **vi**

Contents **viii**

List of Figures **xi**

List of Tables **xiii**

1 INTRODUCTION **1**

1.1 Background 1

1.2 Problem Formulation 3

1.3 Objective 3

1.4 Scope of Problem 3

1.5 Research Methodology 4

1.6 Writing Systematics 4

2 BASIC CONCEPT **5**

2.1 Internet of Things (IoT) 5

2.2 IoT Sub-System 5

2.3 Unmanned Aerial Vehicle (UAV) 6

2.4 Quadcopter 7

2.4.1 Lithium Polymer (LiPo) Battery 8

2.4.2 Brushless DC (BLDC) Motor 9

2.4.3 Electronic Speed Controller (ESC) 10

2.5 Navigation System in Quadcopter 11

2.5.1 Global Positioning System (GPS) 11

2.5.2 Pixhawk 12

2.5.3	Inertial Measurement Unit (IMU)	12
2.6	Telemetry	13
2.7	Latitude	13
2.8	Longitude	14
2.9	Altitude	14
2.10	Dilution of Precision (DOP)	15
2.11	Ground Control Station (GCS)	15
2.12	Mission Planner	15
2.12.1	Take Off	16
2.12.2	Waypoint (WP)	16
2.12.3	Return to Launch (RTL)	16
2.13	Standard Deviation	17
3	SYSTEM METHOD	18
3.1	Design System	18
3.2	The Schematic of Overall System	19
3.3	Tools Specification	19
3.3.1	Hardware	19
3.3.2	Software	22
3.4	Mission Path	22
3.5	Preflight Parameter Check	23
3.6	Preflight Flowchart	24
3.7	Mission Flight Flowchart	25
3.8	Testing Scenarios	26
4	RESULT AND ANALYSIS	27
4.1	Software Testing	27
4.2	ATOL System Testing on Quadcopter	29
4.3	GPS Precision on The Take Off and Landing Coordinate	31
4.4	Take Off Coordinate on Quadcopter	32
4.5	Landing Coordinate on Quadcopter	33
4.6	Waypoint 1 Altitude	34
4.7	Waypoint 2 Altitude	35
4.8	Test Result	37
5	CONCLUSION AND SUGGESTION	38
5.1	Conclusion	38
5.2	Suggestion	38

Bibliography

39

APPENDICES