

DAFTAR PUSTAKA

- [1] Sustek, Michal Urednicek, Zdeněk, "The Basics of Quadcopter Anatomy," *MATEC Web of Conferences*, vol. 210, pp. 1-7, 2018.
- [2] Lindberg, Robert, "MASTER'S THESIS Autonomous Takeoff and Landing for Quadcopters," 2015.
- [3] Yang, Shaowu Scherer, Sebastian A. Zell, Andreas, "An onboard monocular vision system for autonomous takeoff, hovering and landing of a micro aerial vehicle," *Journal of Intelligent and Robotic Systems: Theory and Applications*, vol. 69, no. 1-4, pp. 499-515, 2013.
- [4] Khazraj, Hesam Faria Da Silva, F. Bak, Claus Leth, "A performance comparison between extended Kalman Filter and unscented Kalman Filter in power system dynamic state estimation," *Proceedings - 2016 51st International Universities Power Engineering Conference, UPEC 2016*, Vols. 2017-Janua, pp. 1-6, 2017.
- [5] Lugo, Jacobo Jiménez Zell, Andreas, "Framework for autonomous on-board navigation with the AR.Drone," *Journal of Intelligent and Robotic Systems: Theory and Applications*, vol. 73, no. 1-4, pp. 401-412, 2014.
- [6] Isaac Saito, "wiki ROS.org," 22 Maret 2016. [Online]. Available: <http://wiki.ros.org/APIs..>
- [7] Foote, Tully, "Ros.org," Open Source Robotics Foundation, 11 June 2020. [Online]. Available: <http://wiki.ros.org/>. [Accessed 11 June 2020].
- [8] Atoev, Sukhrob Kwon, Ki Ryong Lee, Suk Hwan Moon, Kwang Seok, "Data analysis of the MAVLink communication protocol," *2017 International Conference on Information Science and Communications Technologies, ICISCT 2017*, Vols. 2017-Decem, pp. 1-3, 2017.

- [9] Dronecode, "PX4 Dev Team," Dronecode, The Linux Foundation, 17 07 2020. [Online]. Available: <https://dev.px4.io/v1.9.0/en/>.
- [10] Dronecode, "Simulation," Linux Foundation, 17 July 2020. [Online]. Available: <https://dev.px4.io/v1.9.0/en/simulation/#sitr-simulation-environment>.
- [11] Analytics., Charles River, "robot_localization," Sphinx 1.6.7., 2016. [Online]. Available: http://docs.ros.org/melodic/api/robot_localization/html/index.html.
- [12] Mohamed, Sherif A.S.Hagbayan, Mohammad Hashem Westerlund, Tomi Heikkonen, Jukka Tenhunen, Hannu Plosila, Juha, "A Survey on Odometry for Autonomous Navigation Systems," *IEEE Access*, vol. 7, pp. 97466-97486, 2019.
- [13] Riseborough, Paul, "'PX4 State Estimation' PX4 Developer Summit Zurich 2019," in *PX4 Autopilot - Open Source Flight Control.*, 2019.