

## DAFTAR GAMBAR

Gambar 2. 1 Model quadcopter .....	5
Gambar 2. 2 Putaran Motor quadcopter .....	5
Gambar 2. 3 Diagram blok kontroler PID .....	6
Gambar 3.1 Simulasi SITL . .....	14
Gambar 3.2 Diagram Block EKF .....	16
Gambar 3.3 Grafik node dan topic pada sistem .....	17
Gambar 3.4 Aliran pesan mavlink .....	19
Gambar 3.5 Gazebo Simulasi .....	19
Gambar 3.6 QGroundControl .....	20
Gambar 3.7 Rat_bag .....	20
Gambar 4.1 Implementasi Rangkain Skematik Simulasi .....	21
Gambar 4.2 Membuat node package robot localozation.....	22
Gambar 4.3 Frekuensi sensor input dan output .....	22
Gambar 4.4 Informasi 3D .....	23
Gambar 4.5 Set Frame .....	23
Gambar 4.6 Set Topic .....	24
Gambar 4.7 Filter Sate .....	24
Gambar 4.8 Diffrential.....	24
Gambar 4.9 Parameter relative.....	25
Gambar 4.10 Gravitasi dan diagnostics .....	25
Gambar 4.11 Set debug.....	26
Gambar 4.12 Covert gps to UTM .....	26
Gambar 4.13 Pembuatan topic baru .....	27
Gambar 4.14 Pembuatan Misi Pertama.....	27
Gambar 4.15 Plot Odometry imu 5m.....	28
Gambar 4.16 Plot Odometry imu EKF 5m .....	28
Gambar 4.17 Plot Odometry imu 5m.....	29
Gambar 4.18 Plot Odometry imu EKF 5m .....	29
Gambar 4.19 Plot Odometry imu10m.....	30
Gambar 4.20 Plot Odometry imu EKF 10m .....	30
Gambar 4.21 Plot Odometry imu 10m.....	31
Gambar 4.22 Plot Odometry imu EKF 10m .....	31