

Daftar Pustaka

- [1] G. Information, "3D Disaster Management."
- [2] D. J. Nallathambi, "Comprehensive Evaluation of the Performance of Rescue Robots using Victim Robots," *2018 4th Int. Conf. Control. Autom. Robot.*, pp. 60–64, 2018.
- [3] S. A. Fattah *et al.*, "Dynamic map generating Rescuer offering surveillance robotic system with autonomous path feedback capability," *IEEE Reg. 10 Humanit. Technol. Conf. R10-HTC 2015 - co-located with 8th Int. Conf. Humanoid, Nanotechnology, Inf. Technol. Commun. Control. Environ. Manag. HNICEM 2015*, 2016.
- [4] J. Chang, R. Wang, and W. Wang, "A real time terrain recognition method for mobile robot moving," pp. 7–10, 2016.
- [5] F. Edalatfar, S. Hajhashemi, B. Yaghootkar, and B. Bahreyni, "Dual mode resonant capacitive MEMS accelerometer," *IEEE 3rd Int. Symp. Inert. Sensors Syst. ISS 2016 - Proc.*, pp. 97–100, 2016.
- [6] Otaviousp, "Angle Measurement Using Gyro, Accelerometer and Arduino," 2010. [Online]. Available: <https://www.instructables.com/id/Angle-measurement-using-gyro-accelerometer-and-Ar/>. [Accessed: 29-Oct-2018].
- [7] A. Blessed Joshua, J. Jenita Grace, and A. M. George, "Open CV pattern based smart bank security system with theft & identification using Android," *Proc. 2016 2nd Int. Conf. Appl. Theor. Comput. Commun. Technol. iCATccT 2016*, pp. 254–257, 2017.
- [8] J. B, S. V, V. Purohit, D. Oswald Tauro, and V. J, "Design and Development of Automated Intelligent Robot Using OpenCV," *2018 Int. Conf. Des. Innov. 3Cs Comput. Commun. Control*, pp. 92–96, 2018.
- [9] P. Viola and M. Jones, "viola-Jones_IJCVRobust Real-time Object Detection.pdf," pp. 1–25, 2001.
- [10] H. A. Patel and D. G. THakore, "Moving Object Tracking Using Kalman Filter 2," vol. 2, no. April, p. 4201376, 2013.