

## DAFTAR PUSTAKA

- [1] K. Bijanrostami, “Design and Development of an Automated Guided Vehicle for Educational Purposes,” no. September, 2011.
- [2] N. Hayat, D. Khushi, and M. Rashid, “Algorithm for Line Follower Robots to Follow Critical Paths with Minimum Number of Sensors,” vol. 4523, pp. 13–22.
- [3] N. T. Jayanti, A. Rusdinar, D. Ph, and A. S. Wibowo, “PERANCANGAN SISTEM PENGONTROLAN PERGERAKAN AUTOMATED GUIDED VEHICLE ( AGV ) UNTUK MENARIK TROLI MENGGUNAKAN SENSOR LIDAR DESIGN OF AUTOMATED GUIDED VEHICLE ( AGV ) MOVEMENT CONTROL SYSTEM FOR PULLING TROLLEY USING LIDAR SENSOR,” vol. 4, no. 2, pp. 1596–1603, 2017.
- [4] J. Nádvořník and P. Smutný, “Remote Control Robot Using Android Mobile Device,” no. May 2014, 2018.
- [5] A. Satrio, B. Pratama, A. Rusdinar, E. Susanto, F. T. Elektro, and U. Telkom, “KONTROL KESTABILAN GERAK ROBOT LINE FOLLOWER DENGAN ACCELEROMETER DAN GYROSCOPE MENGGUNAKAN METODE LOGIKA FUZZY DESIGN AND IMPLEMENTATION OF AUTOMATED GUIDED VEHICLE ( AGV ) WITH DIRECTION CONTROL SYSTEM IN FRONT WHEEL USING FUZZY,” vol. 2, no. 2, pp. 2108–2115, 2015.
- [6] S. Sondhia, S. S. Hegde, S. Chakole, and V. Vora, “DEVELOPMENT OF SELF BALANCING ROBOT WITH PID CONTROL,” vol. 7, no. 1, pp. 1–6, 2017.
- [7] H. A. Rahardjo, I. P. Pangaribuan, and A. S. Wibowo, “IMPLEMENTASI KONTROLER PID PADA SISTEM KONTROL KECEPATAN PUTAR MOTOR DC UNTUK MOBIL ANAK BERBASIS ANDROID PID

CONTROLLER IMPLEMENTATION IN DC MOTOR ANGULAR SPEED,”  
vol. 3, no. 3, pp. 4089–4096, 2016.

- [8] T. Astrom, K. and Hagglund, “PID Controllers : Theory, Design, and Tuning.” .
- [9] R. A. Saputra, P. Pangaribuan, I. Prasetya, and D. Wibawa, “RANCANG BANGUN MAGNET LEVITATION BALL MENGGUNAKAN PID KONTROLER DAN ANALISIS ROBUST KONTROL BERBASIS ARDUINO UNO DESIGN OF THE MAGNETIC LEVITATION BALL USING PID CONTROLLER AND ROBUST CONTROL ANALYSIS BASED ON ARDUINO UNO,” vol. 3, no. 3, pp. 4271–4280, 2016.