

REFERENSI

- [1] Richard Haberman, "Mathematical Models: Mechanical Vibrations, Population Dynamics, and Traffic Flow. Volume 21". SIAM. 1998.
- [2] Ofyar Z. Tamin, "Perencanaan & Pemodelan Transportasi. Edisi Kedua". 1997.
- [3] M. Treiber, A. Kesting, "Traffic Flow Dynamics: Data, Models and Simulation. Springer". 2012.
- [4] M. Treiber, A. Kesting, D. Helbing, "MOBIL: General Lane-Changing Model for Car-Following Models". 2006.
- [5] M. Treiber, A. Kesting, "A. Modeling lane-changing decisions with MOBIL".
- [6] S. Jin, Zhi-yi Huang, Peng-fei Tao, Dian-hai Wang, "Car-following theory of steady-state traffic flow using time-to-collision". 2011.
- [7] Johan Janson Olstam, Andreas Tapani, "Comparison of Car-Following Models". 2004.
- [8] Heikki Sumala, "Brake Reaction Times and Driver Behavior Analysis". 2000.
- [9] Tomer Toledo, "Driving Behavior: Models and Challenges". 2006.
- [10] Janert, "Gnuplot in Action". Manning Publications Co. 2010.