

## DAFTAR PUSTAKA

- [1] L. Blitzer, *Inverted Pendulum*, vol. 33, no. 12. 1965.
- [2] L. H. Yu and F. Jian, “An Inverted Pendulum Fuzzy Controller Design and Simulation,” *2014 Int. Symp. Comput. Consum. Control*, vol. 1, pp. 557–559, 2014.
- [3] S. Reza Dwi Imami, Aris Triwiyatno, “DESAIN KONTROL INVERTED PENDULUM DENGAN METODE KONTROL ROBUST FUZZY,” vol. VOL.2, NO., 2013.
- [4] P. . hindriyanto dwi purnomo, *Logika Fuzzy*. 2014.
- [5] E. Etanol, D. Waru, and G. Hibiscus, *PERANCANGAN SISTEM ROBOT PENGUKUR KONDISI JALAN BERBASIS FUZZY LOGIC*. 2017.
- [6] M. M. Bachtiar, B. S. B. D, and A. R. A. Besari, “Sistem Kontrol Inverted Pendulum Pada Balancing Mobile Robot,” pp. 978–979, 2015.
- [7] A. Marzuki, “Pulse Width Modulation ( PWM ),” pp. 1–4, 2015.
- [8] Infineon technologies, “Datasheet BTS7690,” .
- [9] Autonics, “Datasheet EP50S,” pp. 48–52.