DAFTAR SINGKATAN

UAV	*Unmanned Aerial Vehicle*
GPS	*Global Positioning System*
RTL	*Return to Launch*
ESC	*Electronic Speed Controller*
PID	*Proportional Integral Derivatif*
LiPo	*Lithium Polymer*
RC	*Remote Control*
PWM	*Pulse Width Modulation*
DC	*Direct Current*
Rx	*Receiver*
Tx	*Transmitter*
GUI	*Graphical User Interface*