

DAFTAR SINGKATAN

MCL	: Monte Carlo Localization
ROS	: Robot Operating System
Tx	: Transmitter
Rx	: Receiver
WD	: Wheel Drive
SLAM	: Simultaneous Localization and Mapping
Rviz	: ROS Visualization
AMCL	: Adaptive Monte Carlo Localization
ADC	: Analog to Digital Conversion
LED	: Light Emitting Diode