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| AI | Artificial Intelligence |
| AP | Average Precision |
| AV | Autonomous Vehicle |
| BiFPN | Bidirectional Feature Pyramid Network |
| CCTV | Closed Circuit Television |
| CDF | Current Data Fitting |
| CNN | Convolutional Neural Network |
| CPU | Central Processing Unit |
| FLOPS | Floating Point Operations per Second |
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| FN | False Negative |
| FP | False Positive |
| FPS | Frame Per Second |
| GPU | Graphics Processing Unit |
| IMU | Inertial Measurement Unit |
| IoU | Intersection over Union |
| LIDAR | Light Detection and Ranging |
| mAP | Mean Average Precision |
| MD | Manhattan Distance |
| MSE | Mean Squared Error |
| NH | Non-Homogeneous |
| NMS | Non Maximum Supression |
| OS | Operating System |
| PSNR | Peak Signal to Noise Ratio |
| RAM | Random Access Memory |
| SSIM | Structural Similarity |
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| SSS | Smart Surveillance System |
| TL | Transfer Learning |
| TN | True Negative |
| TP | True Positive |