

# **Design and Implementation of Q-Learning for Mobile Robot Navigation in Dynamic Environments**

A THESIS DRAFT SUBMITTED TO  
THE SCHOOL OF ELECTRICAL ENGINEERING

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**2101182035**



IN PARTIAL FULFILLMENT OF THE REQUIREMENTS FOR THE DEGREE  
OF  
MASTER OF ELECTRICAL ENGINEERING  
IN  
THE SCHOOL OF ELECTRICAL ENGINEERING

**TELKOM UNIVERSITY  
2022**